

Algorithms for computing a planar homography from conics in correspondence

Juho Kannala, Mikko Salo, and Janne Heikkilä

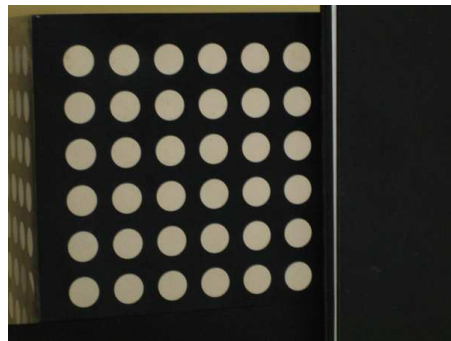
Machine Vision Group

University of Oulu

Finland

Introduction

This presentation deals with the computation of a planar homography from conic correspondences.



$H ?$
→



Two new algorithms are proposed:

- a linear SVD-based algorithm for the case of three or more correspondences
- another algorithm for the minimal case of two correspondences

Both algorithms use only linear algebra and are easy to implement.

Background

The transformation between two perspective views of a plane is a homography.

- Most often the homography is computed from point correspondences.
- Also conics have been used

[1] Sugimoto: A linear algorithm for computing the homography from conics in correspondence. *Journal of Mathematical Imaging and Vision*, 2000.

[2] Mudigonda et. al: Geometric structure computation from conics. ICVGIP, 2004.

Background

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 - [2] Mudigonda et. al: Geometric structure computation from conics. ICVGIP, 2004.
- The proposed SVD-based algorithm requires only 3 correspondences while that in [1] requires 7.
- The proposed algorithm for 2 correspondences does not require solving polynomial equations as that in [2].

Properties of conics

In homogeneous coordinates, a general conic section C is represented with a real symmetric 3×3 matrix,

$$\mathbf{x}^\top \mathbf{C} \mathbf{x} = 0.$$

Under the point homography $\mathbf{x}' = \mathbf{H}\mathbf{x}$ a conic C transforms to $\mathbf{C}' = \mathbf{H}^{-\top} \mathbf{C} \mathbf{H}^{-1}$.

Due to undetermined scale the correspondence constraint

$$\mathbf{C}' \sim \mathbf{H}^{-\top} \mathbf{C} \mathbf{H}^{-1}$$

provides 5 scalar constraints while the homography has 8 degrees of freedom. Hence, at least two correspondences are required.

General case: n correspondences

Assume that we have the conic correspondences $C_i \leftrightarrow C'_i$, between two-planes related by a homography \mathbf{H} . Further, assume that $\det C_i \neq 0$, $\det C'_i \neq 0$, $\det \mathbf{H} \neq 0$.

By fixing $\det \mathbf{H} = 1$ and normalizing the conics so that $\det C_i = \det C'_i$ we get

$$C_i = \mathbf{H}^\top C'_i \mathbf{H}, \quad i = 1, \dots, n$$

Any two of the above equations gives

$$C_i^{-1} C_j = \mathbf{H}^{-1} C_i'^{-1} C_j' \mathbf{H}.$$

This can be written in the form

$$C_i'^{-1} C_j' \mathbf{H} - \mathbf{H} C_i^{-1} C_j = 0$$

which is a set of linear equations in the elements of \mathbf{H} .

General case: n correspondences

The linear equations can be written in the form

$$\mathbf{M}_{ij} \mathbf{h} = \mathbf{0},$$

where \mathbf{h} is a 9×1 vector containing the elements of \mathbf{H} and \mathbf{M}_{ij} is a 9×9 matrix determined by the conics.

By considering all ordered pairs among the n conics we get an overdetermined set of $9n(n - 1)$ equations

$$\mathbf{M} \mathbf{h} = \mathbf{0}$$

so that the null space is usually one dimensional when $n \geq 3$.

In practice, the solution minimizing $\|\mathbf{M} \mathbf{h}\|$ with $\|\mathbf{h}\| = 1$ is obtained by SVD. If desired, one may scale the elements of \mathbf{h} so that $\det \mathbf{H} = 1$.

Algorithm, $n \geq 3$

- (i) Given the conic correspondences normalize all the coefficient matrices to have unit Frobenius norm. Denote the obtained matrices by $\mathbf{C}_i, \mathbf{C}'_i, i = 1, \dots, n$. Then, for all i , replace \mathbf{C}_i with $s_i \mathbf{C}_i$ where $s_i = \left(\frac{\det \mathbf{C}'_i}{\det \mathbf{C}_i} \right)^{1/3}$.
- (ii) For each ordered pair $\{i, j\}, i, j = 1, \dots, n$, compute $\mathbf{C}_i^{-1} \mathbf{C}_j$ and $\mathbf{C}'_i^{-1} \mathbf{C}'_j$ and use these to form the matrices \mathbf{M}_{ij} .
- (iii) Stack all the matrices \mathbf{M}_{ij} to a $9n(n-1) \times 9$ matrix \mathbf{M} and compute its singular value decomposition $\mathbf{M} = \mathbf{U}\mathbf{S}\mathbf{V}^\top$ so that the singular values are in descending order on the diagonal of \mathbf{S} . Set \mathbf{h} to be the last column of \mathbf{V} .
- (iv) The vector \mathbf{h} contains the elements of the homography matrix \mathbf{H} (if the configuration of conics is such that they determine the homography uniquely).

Minimal case: 2 correspondences

Lemma. *If \mathbf{C} is real symmetric then $\mathbf{C} = \mathbf{F}\mathbf{F}^\top$ for some \mathbf{F} . If \mathbf{C} is invertible and $\mathbf{C} = \mathbf{F}\mathbf{F}^\top = \mathbf{F}_1\mathbf{F}_1^\top$, then $\mathbf{F}_1 = \mathbf{F}\mathbf{R}$ where $\mathbf{R}^\top\mathbf{R} = \mathbf{I}$.*

By fixing again $\det \mathbf{H} = 1$ and $\det \mathbf{C}_i = \det \mathbf{C}'_i$ we get

$$\mathbf{C}_1 = \mathbf{H}^\top \mathbf{C}'_1 \mathbf{H} \quad \Rightarrow \quad \mathbf{F}_1 \mathbf{F}_1^\top = \mathbf{H}^\top \mathbf{F}'_1 \mathbf{F}'_1{}^\top \mathbf{H}$$

$$\mathbf{C}_2 = \mathbf{H}^\top \mathbf{C}'_2 \mathbf{H}.$$

Thus, $\mathbf{H} = \mathbf{F}'_1{}^{-\top} \mathbf{R} \mathbf{F}_1^\top$ and substituting this to the latter equation gives a pair of equations which is equivalent to the original one:

$$\mathbf{R}^\top \mathbf{R} = \mathbf{I},$$

$$\mathbf{R}^\top \mathbf{A} \mathbf{R} = \mathbf{B}.$$

Here \mathbf{R} is the unknown and \mathbf{A} and \mathbf{B} are known complex symmetric matrices.

Minimal case: 2 correspondences

The task is to solve \mathbf{R} from

$$\mathbf{R}^T \mathbf{A} \mathbf{R} = \mathbf{B}.$$

When \mathbf{A} and \mathbf{B} have distinct eigenvalues they are diagonalizable and the solutions are

$$\mathbf{R} = \mathbf{Q} \mathbf{P} \mathbf{U}^T,$$

where \mathbf{Q} and \mathbf{U} contain the eigenvectors of \mathbf{A} and \mathbf{B} , respectively, and

$$\mathbf{P} = \text{diag}(\pm 1, \pm 1, \pm 1).$$

Only four of the above eight choices for \mathbf{P} gives $\det \mathbf{H} = 1$

→ 4 solutions

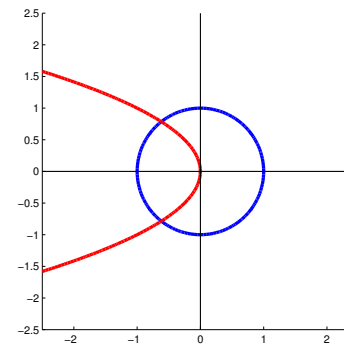
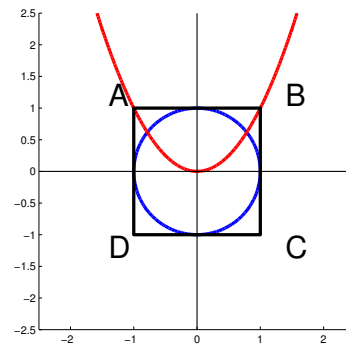
If \mathbf{A} and \mathbf{B} have a multiple eigenvalue and are diagonalizable then there are infinitely many solutions. The case that the matrices are not diagonalizable is possible but unlikely in practice.

Algorithm, $n = 2$

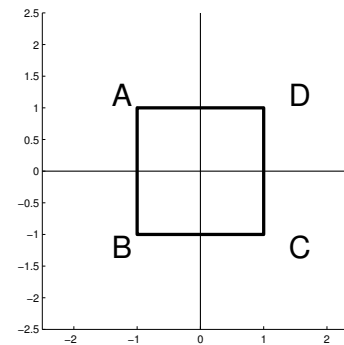
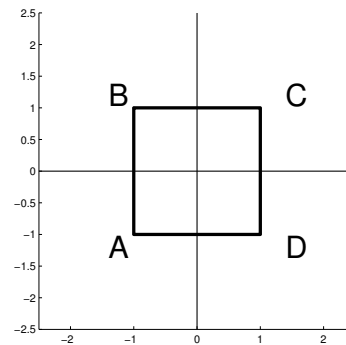
- (i) As before, normalize the conics so that $\det \mathbf{C}_i = \det \mathbf{C}'_i$.
- (ii) Compute the eigendecompositions $\mathbf{C}_1 = \mathbf{V}_1 \mathbf{D}_1 \mathbf{V}_1^\top$ and $\mathbf{C}'_1 = \mathbf{V}'_1 \mathbf{D}'_1 \mathbf{V}'_1{}^\top$ and set $\mathbf{F}_1 = \mathbf{V}_1 \mathbf{D}_1^{1/2}$ and $\mathbf{F}'_1 = \mathbf{V}'_1 \mathbf{D}'_1{}^{1/2}$.
- (iii) Compute $\mathbf{A} = \mathbf{F}'_1{}^{-1} \mathbf{C}'_2 \mathbf{F}'_1{}^{-\top}$ and $\mathbf{B} = \mathbf{F}_1{}^{-1} \mathbf{C}_2 \mathbf{F}_1{}^{-\top}$ and their eigendecompositions $\mathbf{A} = \mathbf{Q} \mathbf{D}_A \mathbf{Q}^\top$ and $\mathbf{B} = \mathbf{U} \mathbf{D}_B \mathbf{U}^\top$ where $\mathbf{D}_A = \text{diag}(a_1, a_2, a_3)$ and $\mathbf{D}_B = \text{diag}(b_1, b_2, b_3)$.
- (iv) Go through all six possible permutations of the eigenvalues b_k and compute distances $\sum_k |a_k - b_k|^2$. Choose the ordering that gives the smallest distance and permute the eigenvectors correspondingly to get a new \mathbf{U} .
- (v) Set $\mathbf{P}_1 = \text{diag}(1, 1, 1)$, $\mathbf{P}_2 = \text{diag}(-1, 1, 1)$, $\mathbf{P}_3 = \text{diag}(1, -1, 1)$ and finally $\mathbf{P}_4 = \text{diag}(1, 1, -1)$. The four solutions are $\mathbf{H}_k = \mathbf{F}'_1{}^{-\top} \mathbf{Q} \mathbf{P}_k \mathbf{U}^\top \mathbf{F}_1{}^\top$, $k = \{1, 2, 3, 4\}$. In general, one of these solutions should be the geometrically correct one.

Simple example

Correspondence of a parabola and a circle under rotation:



Two real solutions, rotation and rotation + reflection:

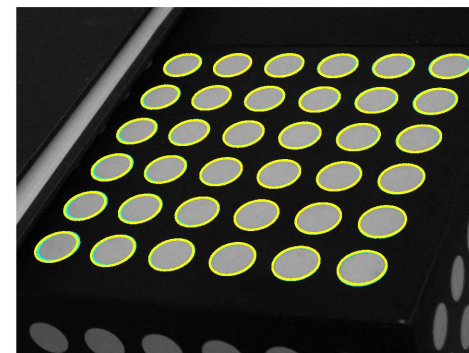
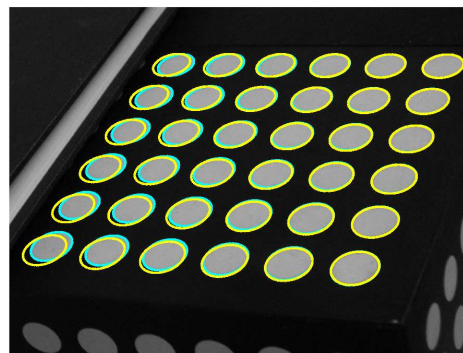
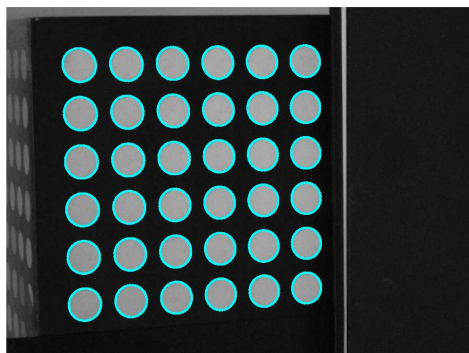


Real example

Two images of a plane containing white circles. The detected ellipses are in cyan. The estimated homography is illustrated in yellow.

Middle: 2 correspondences used

Right: 36 correspondences used



Conclusions

- Two new algorithms were proposed for computing a homography from conic correspondences.
- Both algorithms require only linear algebra and are easy to implement.
- Experiments showed that the algorithms provide a reasonable estimate also when no exact solution exists due to measurement errors in the conic coefficients.

Matlab implementations of the algorithms are available at
<http://www.ee.oulu.fi/~jkannala/>